

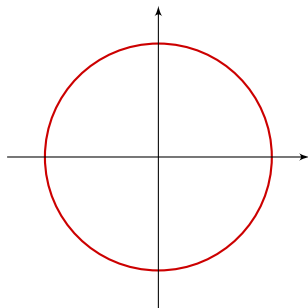
Parametrizing rational algebraic curves using integral bases

Based on a 1994 paper by Mark Van Hoeij

Thibaut Verron

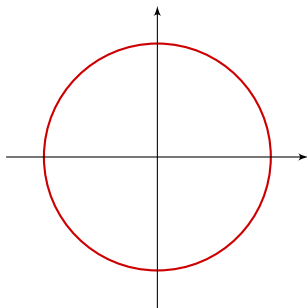
Johannes Kepler University, Institute for Algebra, Linz, Austria

22 October 2020



$$\{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = 1\}$$

Implicit representation



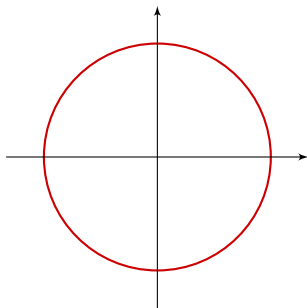
$$\{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = 1\}$$

Implicit representation

$$\left\{ \left(\frac{2t}{t^2 + 1}, \frac{t^2 - 1}{t^2 + 1} \right) : t \in \mathbb{R} \right\}$$

Parametric representation

Algebraic curves and parametrization



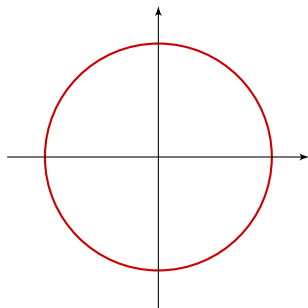
$$\{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = 1\}$$

Implicit representation

↑
Implicitization
(elimination))

$$\left\{ \left(\frac{2t}{t^2 + 1}, \frac{t^2 - 1}{t^2 + 1} \right) : t \in \mathbb{R} \right\}$$

Parametric representation



$$\{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = 1\}$$

Implicit representation

Parametrization

Implicitization
(elimination))

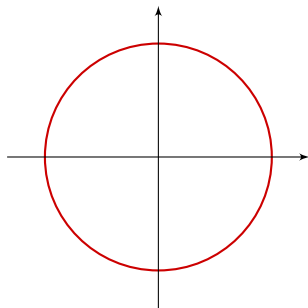
$$\left\{ \left(\frac{2t}{t^2 + 1}, \frac{t^2 - 1}{t^2 + 1} \right) : t \in \mathbb{R} \right\}$$

Parametric representation

Parametrization algorithms:

- ▶ Sendra, Winkler 1991, 1997
- ▶ Van Hoeij 1994, 1996
- ▶ Sendra 2002...

Algebraic curves and parametrization



$$\{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = 1\}$$

Implicit representation

Parametrization

Implicitization
(elimination))

$$\left\{ \left(\frac{2t}{t^2 + 1}, \frac{t^2 - 1}{t^2 + 1} \right) : t \in \mathbb{R} \right\}$$

Parametric representation

Parametrization algorithms:

- ▶ Sendra, Winkler 1991, 1997
- ▶ Van Hoeij 1994, 1996: **use integral bases**
- ▶ Sendra 2002...

- ▶ Let $K = \mathbb{Q}(\alpha) = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q}

- ▶ Let $K = \mathbb{Q}(\alpha) = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q}
- ▶ All elements of K are algebraic
- ▶ Let $\beta \in K$, there exists $a_i, b_i \in \mathbb{Z}$, $d \in \mathbb{N}$ such that

$$\beta^d = \frac{a_0}{b_0} + \frac{a_1}{b_1}\beta + \cdots + \frac{a_{d-1}}{b_{d-1}}\beta^{d-1}$$

- ▶ The **monic minimal polynomial** of β is $\mu_\beta = X^d - \frac{a_{d-1}}{b_{d-1}}X^{d-1} - \cdots - \frac{a_0}{b_0} \in \mathbb{Q}[X]$
(with d minimal)

- ▶ Let $K = \mathbb{Q}(\alpha) = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q}
- ▶ All elements of K are algebraic
- ▶ Let $\beta \in K$, there exists $a_i, b_i \in \mathbb{Z}$, $d \in \mathbb{N}$ such that

$$\beta^d = \frac{a_0}{b_0} + \frac{a_1}{b_1}\beta + \cdots + \frac{a_{d-1}}{b_{d-1}}\beta^{d-1}$$

- ▶ The monic minimal polynomial of β is $\mu_\beta = X^d - \frac{a_{d-1}}{b_{d-1}}X^{d-1} - \cdots - \frac{a_0}{b_0} \in \mathbb{Q}[X]$
(with d minimal)
- ▶ β is **integral** if all the b_i are 1, or equivalently if $\mu_\beta \in \mathbb{Z}[x]$

Integral elements in number fields

- ▶ Let $K = \mathbb{Q}(\alpha) = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q}
- ▶ All elements of K are algebraic
- ▶ Let $\beta \in K$, there exists $a_i, b_i \in \mathbb{Z}$, $d \in \mathbb{N}$ such that

$$\beta^d = \frac{a_0}{b_0} + \frac{a_1}{b_1}\beta + \cdots + \frac{a_{d-1}}{b_{d-1}}\beta^{d-1}$$

- ▶ The monic minimal polynomial of β is $\mu_\beta = X^d - \frac{a_{d-1}}{b_{d-1}}X^{d-1} - \cdots - \frac{a_0}{b_0} \in \mathbb{Q}[X]$
(with d minimal)
- ▶ β is **integral** if all the b_i are 1, or equivalently if $\mu_\beta \in \mathbb{Z}[x]$
- ▶ The set \mathcal{O}_K of integral elements of K is called the **ring of integers** of K

Examples

Recall: $\beta \in \mathcal{O}_K \iff$ its monic minimal polynomial has coefficients in \mathbb{Z}

► $\mathcal{O}_{\mathbb{Q}} = \mathbb{Z}$

Examples

Recall: $\beta \in \mathcal{O}_K \iff$ its monic minimal polynomial has coefficients in \mathbb{Z}

▶ $\mathcal{O}_{\mathbb{Q}} = \mathbb{Z}$

▶ $\mathcal{O}_K \cap \mathbb{Q} = \mathbb{Z}$

Examples

Recall: $\beta \in \mathcal{O}_K \iff$ its monic minimal polynomial has coefficients in \mathbb{Z}

- ▶ $\mathcal{O}_{\mathbb{Q}} = \mathbb{Z}$
- ▶ $\mathcal{O}_K \cap \mathbb{Q} = \mathbb{Z}$
- ▶ Let $K = \mathbb{Q}[i]$, then $\mathcal{O}_K = \mathbb{Z}[i]$

Examples

Recall: $\beta \in \mathcal{O}_K \iff$ its monic minimal polynomial has coefficients in \mathbb{Z}

- ▶ $\mathcal{O}_{\mathbb{Q}} = \mathbb{Z}$
- ▶ $\mathcal{O}_K \cap \mathbb{Q} = \mathbb{Z}$
- ▶ Let $K = \mathbb{Q}[i]$, then $\mathcal{O}_K = \mathbb{Z}[i]$
- ▶ Let $K = \mathbb{Q}[\sqrt{5}]$, then $\varphi = \frac{1 + \sqrt{5}}{2}$ is integral with $\varphi^2 - \varphi - 1 = 0$ and $\mathcal{O}_K = \mathbb{Z}[\varphi]$

- ▶ Let $K = \mathbb{Q}(\alpha) = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q} of degree n
- ▶ $\mathcal{O}_K =$ set of integral elements of K

- ▶ Let $K = \mathbb{Q}(\alpha) = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q} of degree n
- ▶ $\mathcal{O}_K =$ set of integral elements of K
- ▶ \mathcal{O}_K is a ring and a free \mathbb{Z} module with rank n

Integral bases

- ▶ Let $K = \mathbb{Q}(\alpha) = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q} of degree n
- ▶ $\mathcal{O}_K =$ set of integral elements of K
- ▶ \mathcal{O}_K is a ring and a free \mathbb{Z} module with rank n
- ▶ An **integral basis** of K is a basis of \mathcal{O}_K as a \mathbb{Z} -module

Integral bases

- ▶ Let $K = \mathbb{Q}(\alpha) = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q} of degree n
- ▶ $\mathcal{O}_K =$ set of integral elements of K
- ▶ \mathcal{O}_K is a ring and a free \mathbb{Z} module with rank n
- ▶ An integral basis of K is a basis of \mathcal{O}_K as a \mathbb{Z} -module
- ▶ Let $\mathcal{B} = (1, \alpha_1, \dots, \alpha_{n-1})$ be an integral basis of K
- ▶ **Property:** $\beta \in K$ is integral if and only if the coefficients of β in \mathcal{B} are in \mathbb{Z}

Integral bases

- ▶ Let $K = \mathbb{Q}(\alpha) = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q} of degree n
- ▶ $\mathcal{O}_K =$ set of integral elements of K
- ▶ \mathcal{O}_K is a ring and a free \mathbb{Z} module with rank n
- ▶ An integral basis of K is a basis of \mathcal{O}_K as a \mathbb{Z} -module
- ▶ Let $\mathcal{B} = (1, \alpha_1, \dots, \alpha_{n-1})$ be an integral basis of K
- ▶ **Property:** $\beta \in K$ is integral if and only if the coefficients of β in \mathcal{B} are in \mathbb{Z}
- ▶ Integral bases can be effectively computed (Trager, Van Hoeij)

“ Let $K = \mathbb{Q}[X]/\langle f \rangle$ be a finite extension of \mathbb{Q} with degree n .
An element $\beta \in K$ has a monic minimal polynomial $\mu \in \mathbb{Q}[X]$,
and β is integral if $\mu \in \mathbb{Z}[X]$.

The set of integral elements in K is denoted by \mathcal{O}_K ,
it is a free \mathbb{Z} -module with rank n .

An integral basis of K is a basis of \mathcal{O}_K as a \mathbb{Z} -module.

Let $\mathcal{B} = \{1, b_1, \dots, b_{n-1}\}$ be an integral basis of K and $\beta \in K$.
 β is integral if and only if all its coefficients in \mathcal{B} lie in \mathbb{Z} .

”

“ Let $K = k(X)[Y]/\langle f \rangle$ be a finite extension of $k(X)$ with degree n . An element $\beta \in K$ has a monic minimal polynomial $\mu \in k(X)[Y]$, and β is integral if $\mu \in k[X][Y]$.

The set of integral elements in K is denoted by \mathcal{O}_K ,
it is a free $k[X]$ -module with rank n .

An integral basis of K is a basis of \mathcal{O}_K as a $k[X]$ -module.

Let $\mathcal{B} = \{1, b_1, \dots, b_{n-1}\}$ be an integral basis of K and $\beta \in K$.
 β is integral if and only if all its coefficients in \mathcal{B} lie in $k[X]$. ”

- ▶ Let $K = k(X)[Y]/\langle f \rangle$ with f irreducible

- ▶ Let $K = k(X)[Y]/\langle f \rangle$ with f irreducible
- ▶ Elements of K are functions (with poles) on the curve $\mathcal{C} = \{(x, y) \in k^2 : f(x, y) = 0\}$

Integral algebraic functions and poles

- ▶ Let $K = k(X)[Y]/\langle f \rangle$ with f irreducible
- ▶ Elements of K are functions (with poles) on the curve $\mathcal{C} = \{(x, y) \in k^2 : f(x, y) = 0\}$
- ▶ **Property:** $\beta(X, Y) \in K$ is integral if and only if β does not have any pole on \mathcal{C}

Integral algebraic functions and poles

- ▶ Let $K = k(X)[Y]/\langle f \rangle$ with f irreducible
- ▶ Elements of K are functions (with poles) on the curve $\mathcal{C} = \{(x, y) \in k^2 : f(x, y) = 0\}$
- ▶ **Property:** $\beta(X, Y) \in K$ is integral if and only if β does not have any pole on \mathcal{C}
- ▶ β is **locally integral** at x if it does not have any pole at $(x, \bullet) \in \mathcal{C}$

Integral algebraic functions and poles

- ▶ Let $K = k(X)[Y]/\langle f \rangle$ with f irreducible
- ▶ Elements of K are functions (with poles) on the curve $\mathcal{C} = \{(x, y) \in k^2 : f(x, y) = 0\}$
- ▶ **Property:** $\beta(X, Y) \in K$ is integral if and only if β does not have any pole on \mathcal{C}
- ▶ β is **locally integral** at x if it does not have any pole at $(x, \bullet) \in \mathcal{C}$
- ▶ A **local integral basis** of K at $X = x$ is a basis $\mathcal{B} = (1, \alpha_1, \dots, \alpha_{n-1})$ of K such that
 - ▶ All α_i are locally integral at x
 - ▶ $\beta \in K$ is locally integral at x iff its coeffs in \mathcal{B} do not have $X - x$ at the denominator

What is parametrizing?

Data: $f(X, Y) \in k[X, Y]$ irreducible, $\mathcal{C} = \{(x, y) : f(x, y) = 0\}$

Goal: find $x(T), y(T) \in k(T)$ such that

- ▶ for almost all $t \in k$, $(x(t), y(t)) \in \mathcal{C}$
- ▶ for almost all $(x, y) \in \mathcal{C}$, there exists $t \in k$ such that $x = x(t)$, $y = y(t)$

What is parametrizing?

Data: $f(X, Y) \in k[X, Y]$ irreducible, $\mathcal{C} = \{(x, y) : f(x, y) = 0\}$

Goal: find $x(T), y(T) \in k(T)$ such that

- ▶ for almost all $t \in k$, $f(x(t), y(t)) = 0$ in k
- ▶ for almost all $(x, y) \in \mathcal{C}$, there exists $t \in k$ such that $x = x(t)$, $y = y(t)$

What is parametrizing?

Data: $f(X, Y) \in k[X, Y]$ irreducible, $\mathcal{C} = \{(x, y) : f(x, y) = 0\}$

Goal: find $x(T), y(T) \in k(T)$ such that

- ▶ $f(x(T), y(T)) = 0$ in $k(T)$
- ▶ for almost all $(x, y) \in \mathcal{C}$, there exists $t \in k$ such that $x = x(t), y = y(t)$

There is a morphism of fields:

$$k(X)[Y]/\langle f \rangle \longrightarrow k(T)$$

$$X \longmapsto x(T)$$

$$Y \longmapsto y(T)$$

What is parametrizing?

Data: $f(X, Y) \in k[X, Y]$ irreducible, $\mathcal{C} = \{(x, y) : f(x, y) = 0\}$

Goal: find $x(T), y(T) \in k(T)$ such that

- ▶ $f(x(T), y(T)) = 0$ in $k(T)$
- ▶ for almost all $(x, y) \in \mathcal{C}$, there exists a unique $t \in k$ such that $x = x(t), y = y(t)$

There is an injective morphism of fields:

$$k(X)[Y]/\langle f \rangle \longrightarrow k(T)$$

$$X \longmapsto x(T)$$

$$Y \longmapsto y(T)$$

What is parametrizing?

Data: $f(X, Y) \in k[X, Y]$ irreducible, $\mathcal{C} = \{(x, y) : f(x, y) = 0\}$

Goal: find $x(T), y(T) \in k(T)$ such that

- ▶ $f(x(T), y(T)) = 0$ in $k(T)$
- ▶ for almost all $(x, y) \in \mathcal{C}$, there exists a unique $t \in k$ such that $x = x(t), y = y(t)$

There is an isomorphism of fields:

$$k(X)[Y]/\langle f \rangle \longrightarrow k(T)$$

$$X \longmapsto x(T)$$

$$Y \longmapsto y(T)$$

$$t(X, Y) \longleftarrow \longmapsto T$$

What is parametrizing?

Data: $f(X, Y) \in k[X, Y]$ irreducible, $\mathcal{C} = \{(x, y) : f(x, y) = 0\}$

Goal: find $x(T), y(T) \in k(T)$ and $t(X, Y) \in k(X)[Y]/\langle f \rangle$ such that

- ▶ $f(x(T), y(T)) = 0$ in $k(T)$
- ▶ $K(t(X, Y)) = K(X)[Y]/\langle f \rangle$

There is an isomorphism of fields:

$$k(X)[Y]/\langle f \rangle \longrightarrow k(T)$$

$$X \longmapsto x(T)$$

$$Y \longmapsto y(T)$$

$$t(X, Y) \longleftarrow T$$

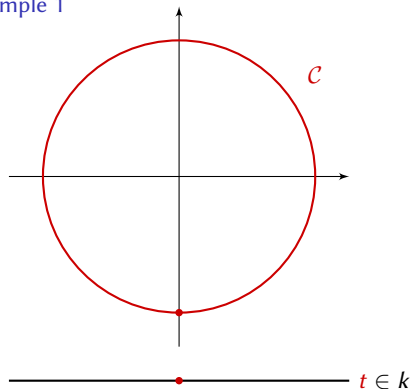
Such a $t(X, Y)$ is called a **parameter** for the curve.

How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

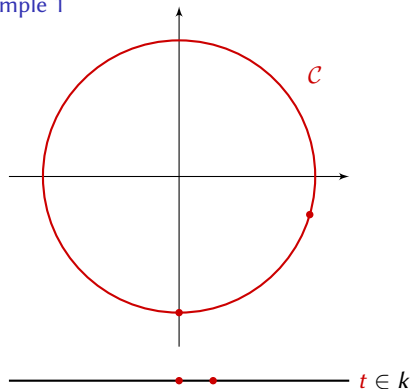


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

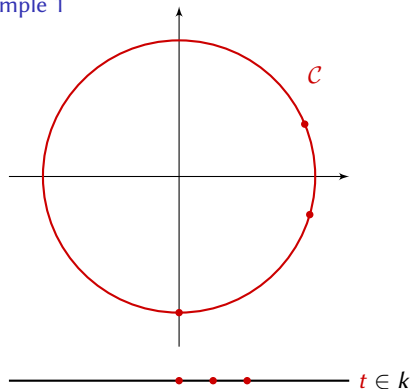


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

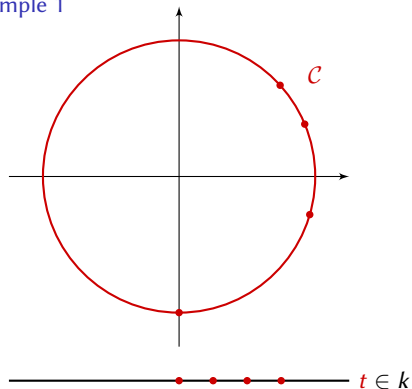


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

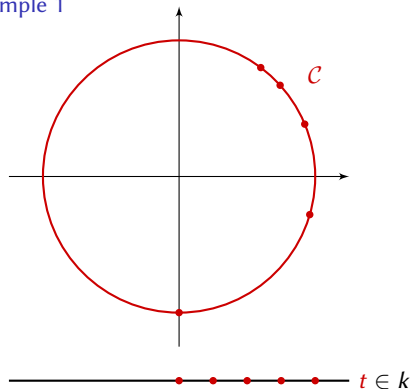


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

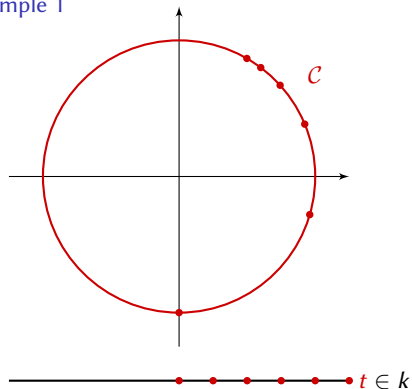


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

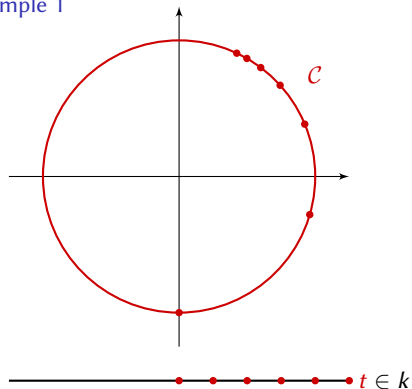


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

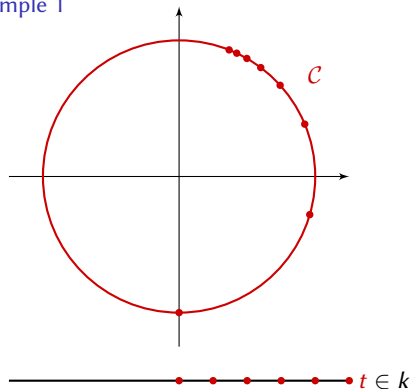


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

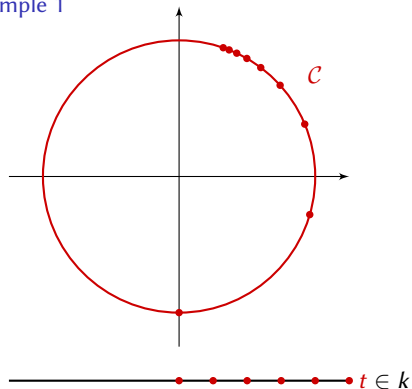


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

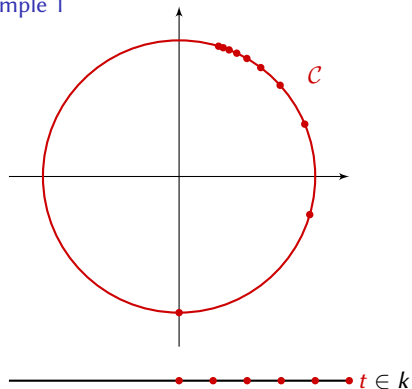


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

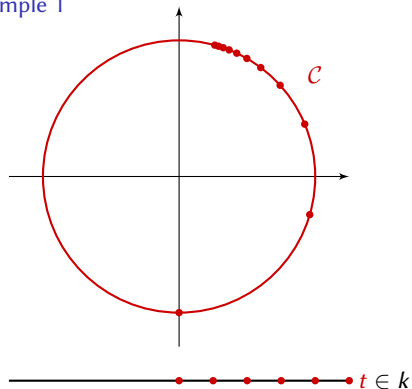


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

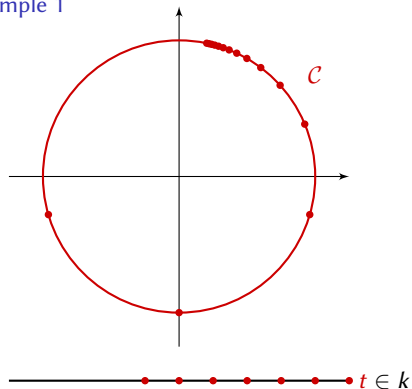


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

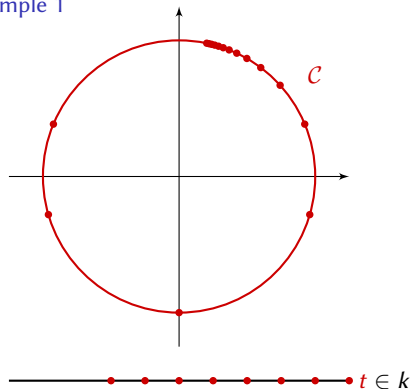


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

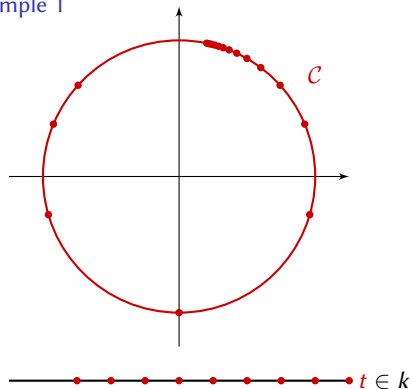


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

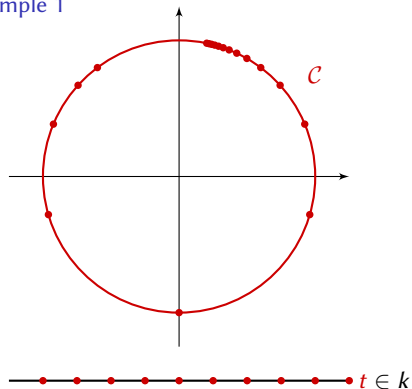


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

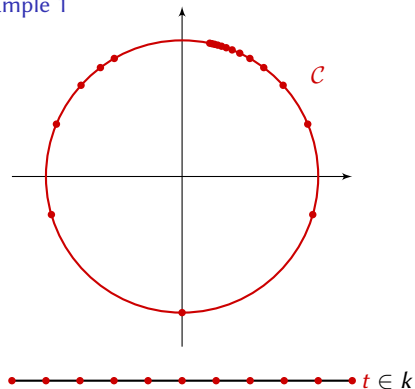


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

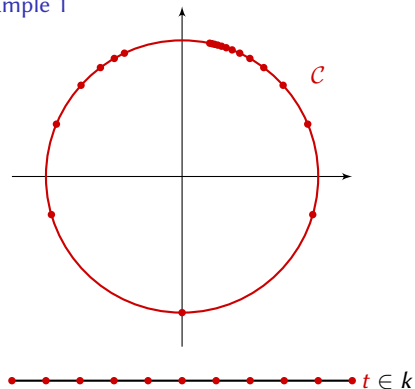


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

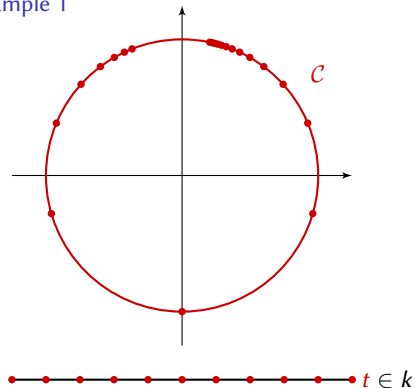


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

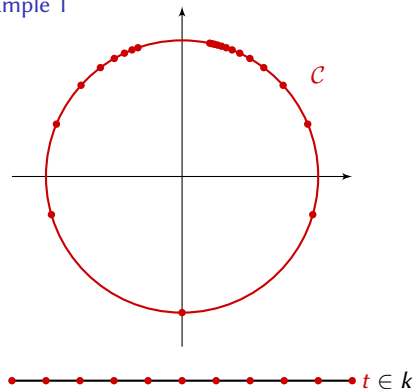


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

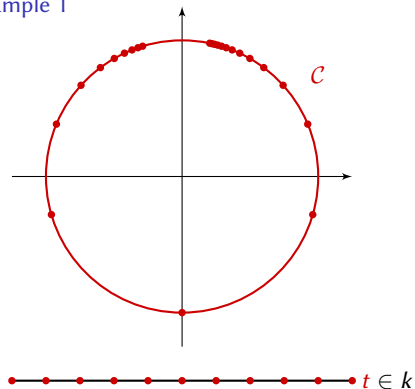


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

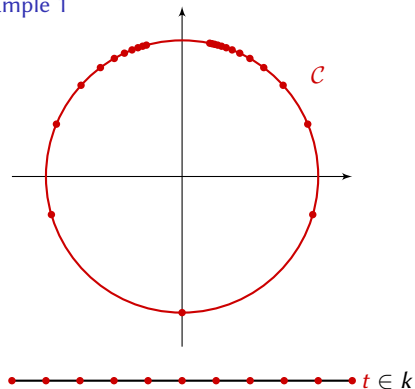


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

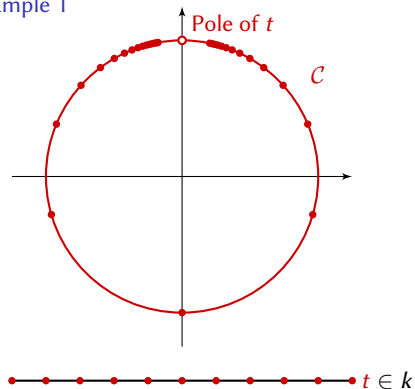


How to compute a parameter?

Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1

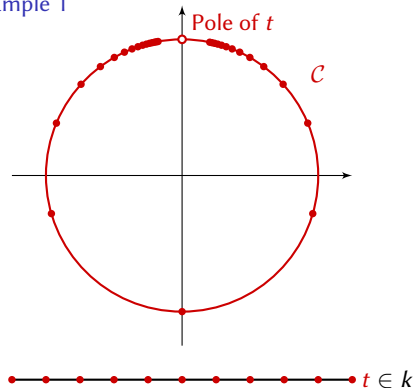


How to compute a parameter?

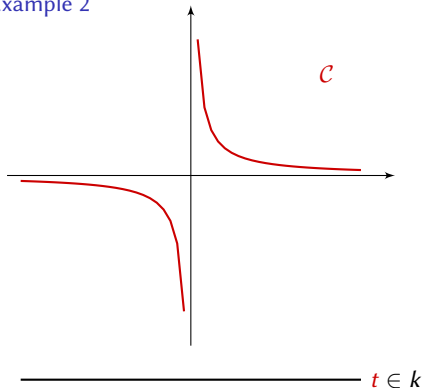
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

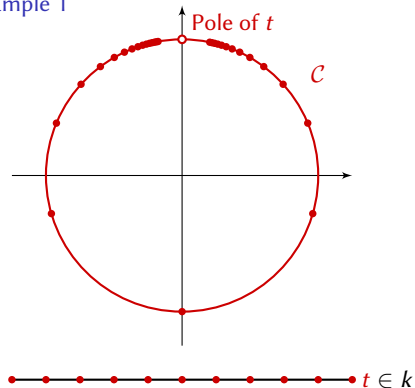


How to compute a parameter?

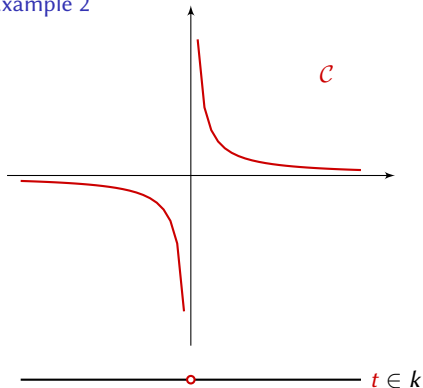
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

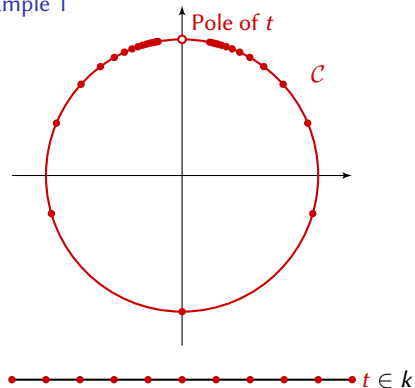


How to compute a parameter?

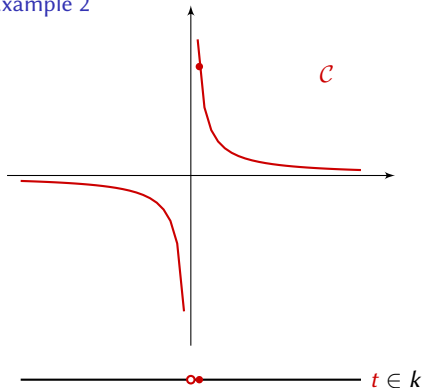
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

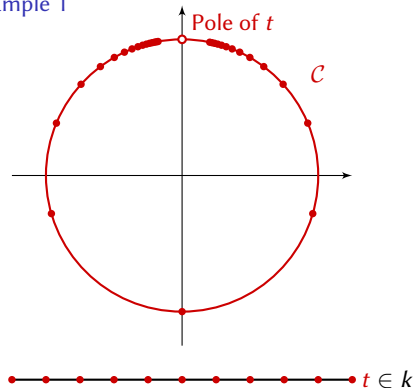


How to compute a parameter?

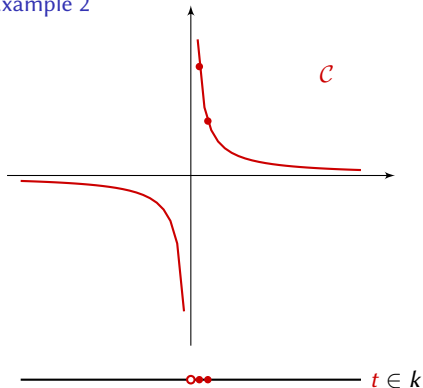
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

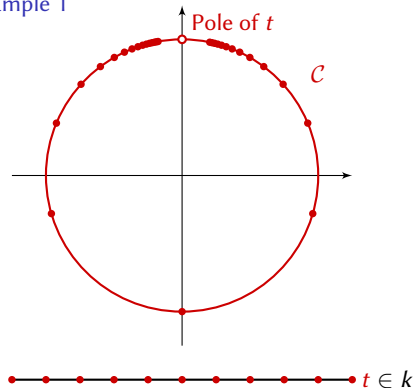


How to compute a parameter?

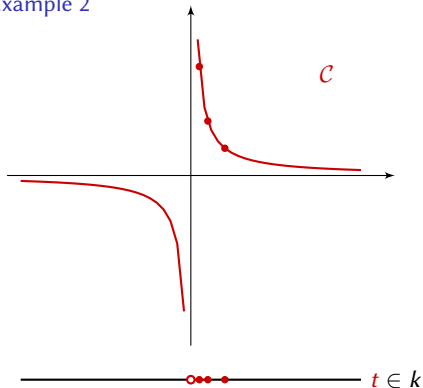
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

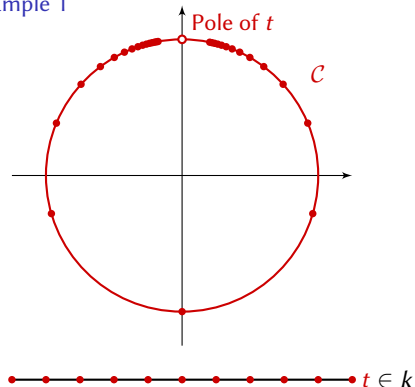


How to compute a parameter?

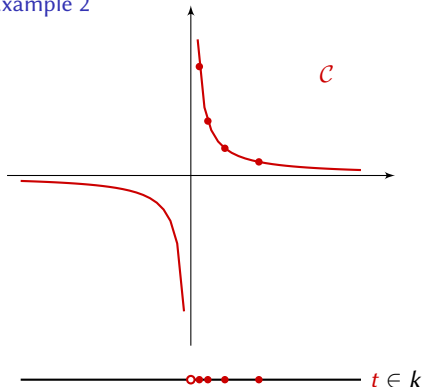
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

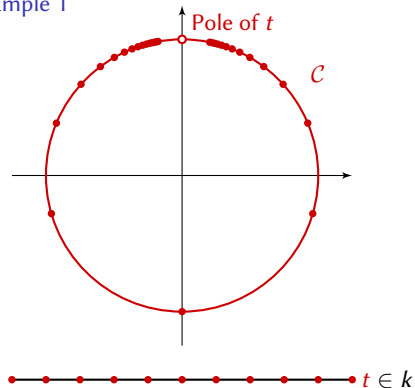


How to compute a parameter?

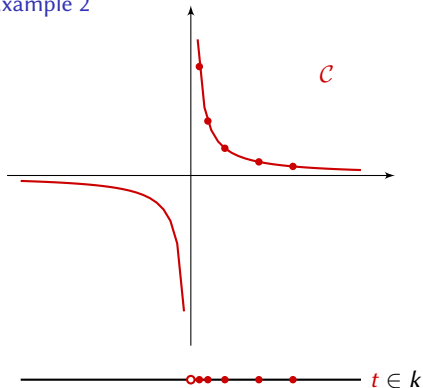
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

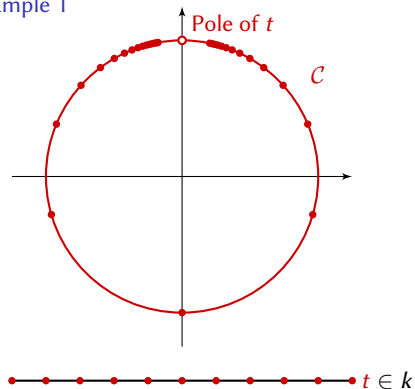


How to compute a parameter?

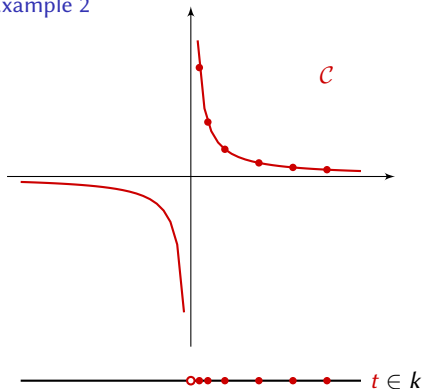
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

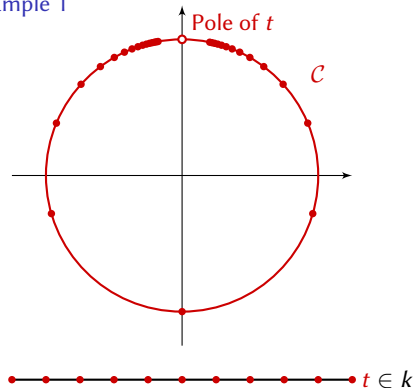


How to compute a parameter?

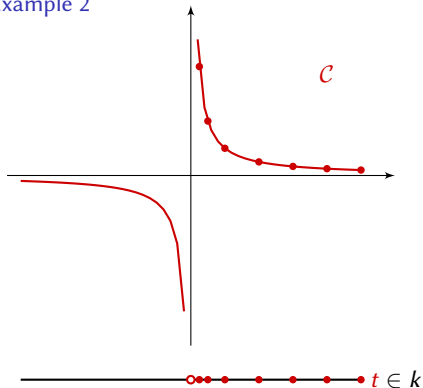
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

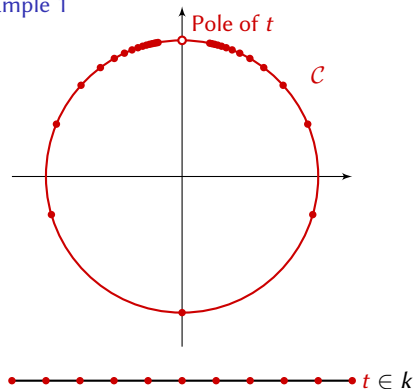


How to compute a parameter?

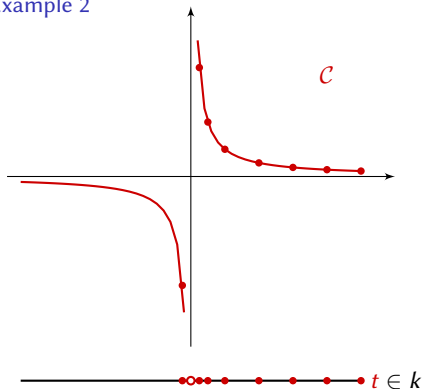
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

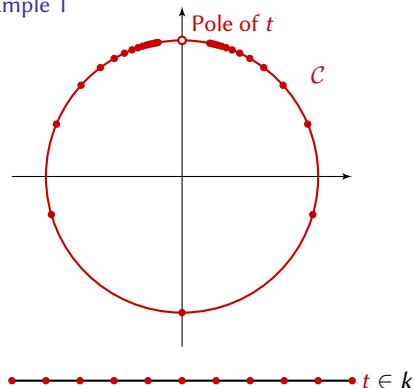


How to compute a parameter?

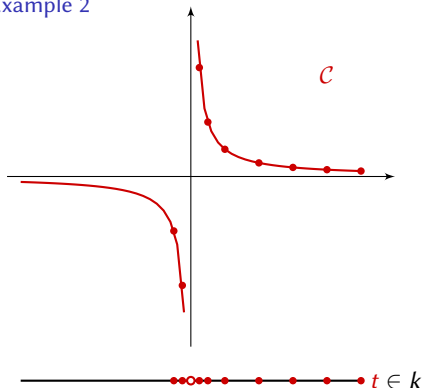
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

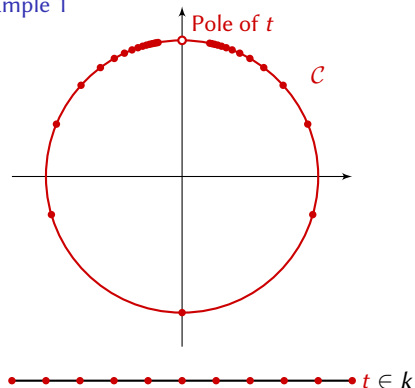


How to compute a parameter?

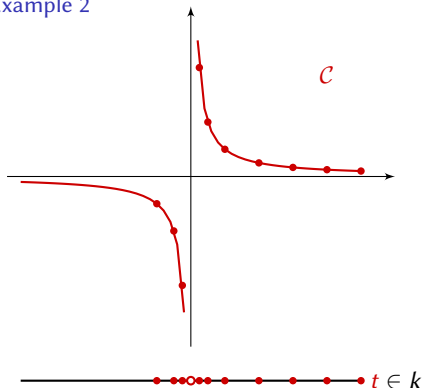
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

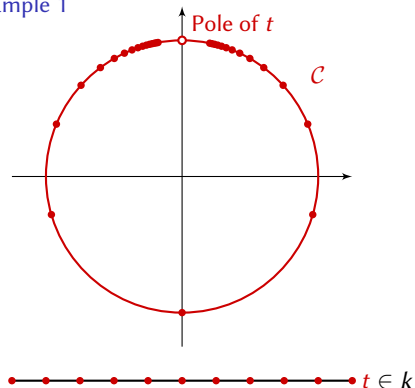


How to compute a parameter?

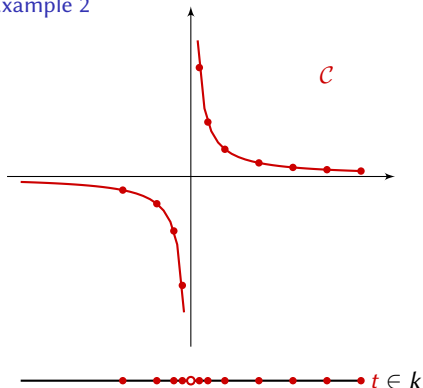
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

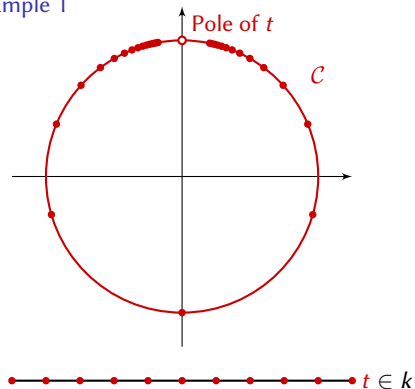


How to compute a parameter?

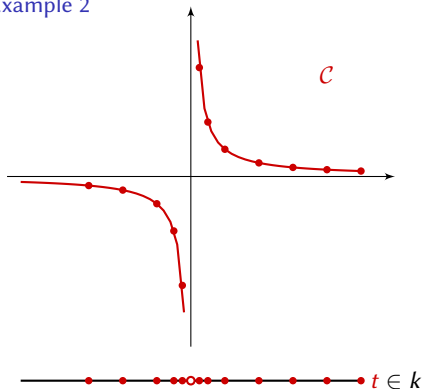
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

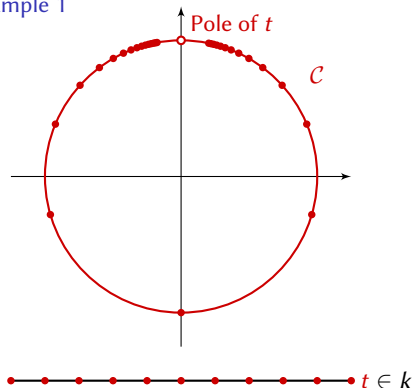


How to compute a parameter?

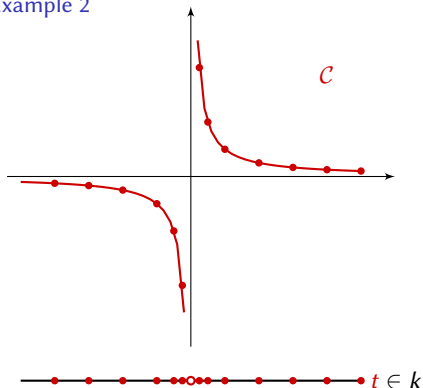
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

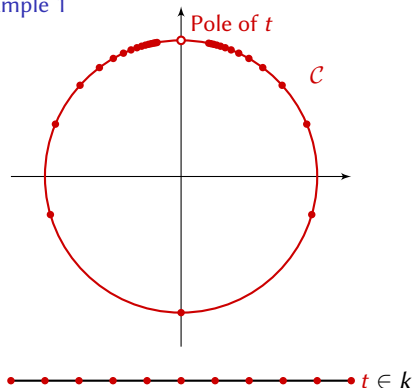


How to compute a parameter?

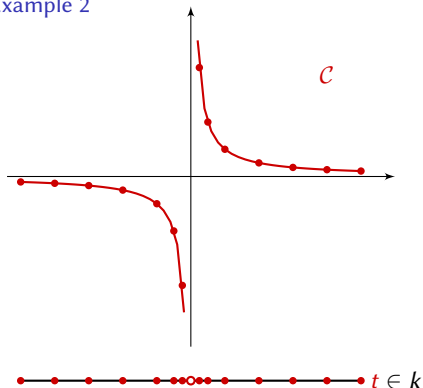
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



Example 2

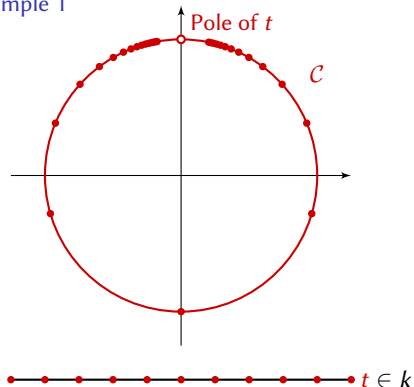


How to compute a parameter?

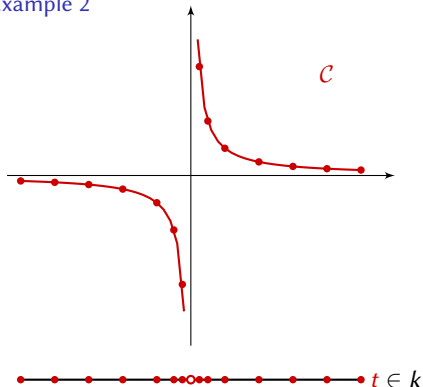
Characterization:

$t(X, Y) \in k(X)[Y]/\langle f \rangle$ is a parameter iff it has exactly one pole, with multiplicity 1, on \mathcal{C}

Example 1



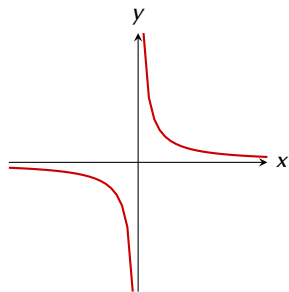
Example 2



Where is the pole of t ?

Points at infinity

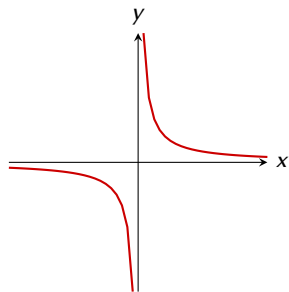
$$f(x, y) = 0$$



$$xy - 1 = 0$$

Points at infinity

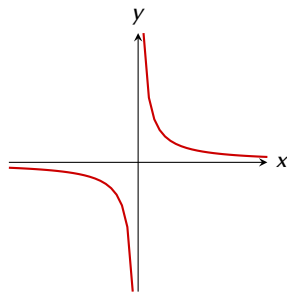
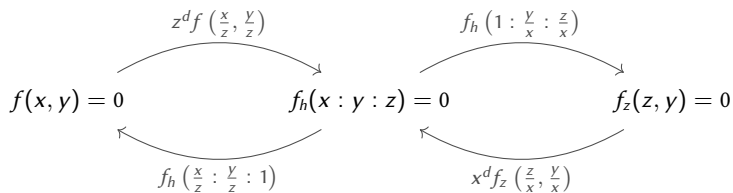
$$\begin{array}{ccc} & z^d f\left(\frac{x}{z}, \frac{y}{z}\right) & \\ \curvearrowright & & \curvearrowleft \\ f(x, y) = 0 & & f_h(x : y : z) = 0 \\ \curvearrowleft & & \curvearrowright \\ & f_h\left(\frac{x}{z} : \frac{y}{z} : 1\right) & \end{array}$$



$$\begin{aligned} xy - 1 &= 0 \\ (z \neq 0) \end{aligned}$$

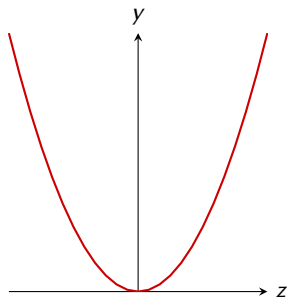
$$xy - z^2 = 0$$

Points at infinity



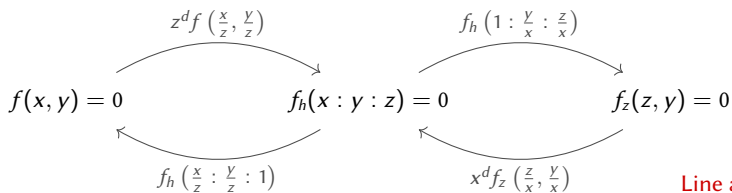
$$\begin{aligned}
 xy - 1 &= 0 \\
 (z \neq 0)
 \end{aligned}$$

$$xy - z^2 = 0$$

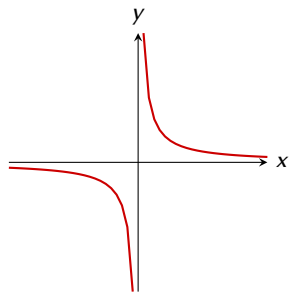


$$\begin{aligned}
 y - z^2 &= 0 \\
 (x \neq 0)
 \end{aligned}$$

Points at infinity

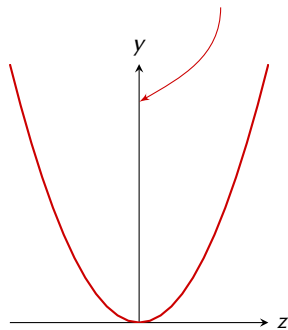


Finite plane



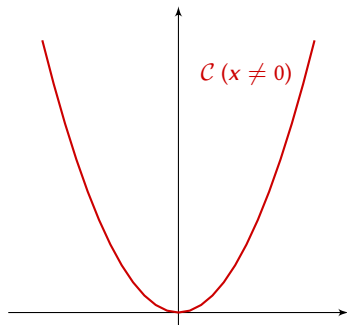
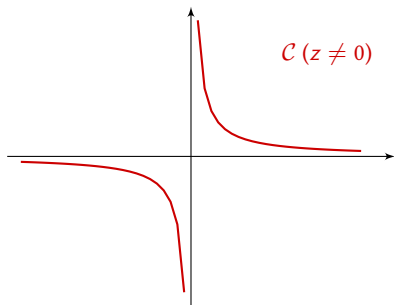
$$\begin{aligned}
 xy - 1 &= 0 \\
 (z \neq 0)
 \end{aligned}$$

Line at infinity
($z = 0$)



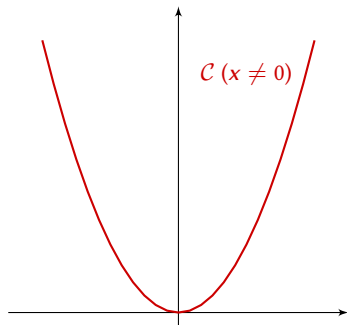
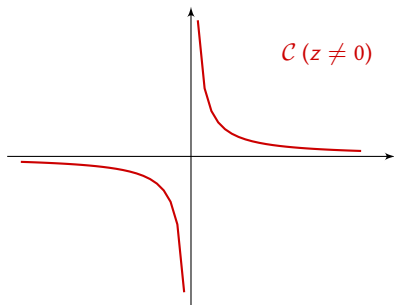
$$\begin{aligned}
 xy - z^2 &= 0 \\
 y - z^2 &= 0 \\
 (x \neq 0)
 \end{aligned}$$


Back to example 2: pole at infinity



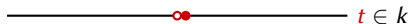
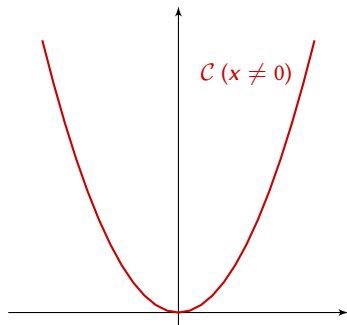
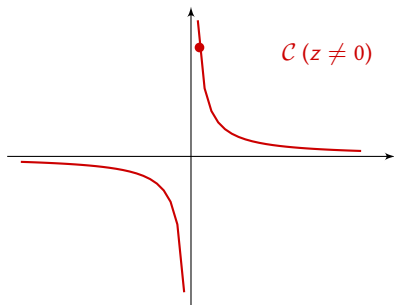
_____ $t \in k$

Back to example 2: pole at infinity

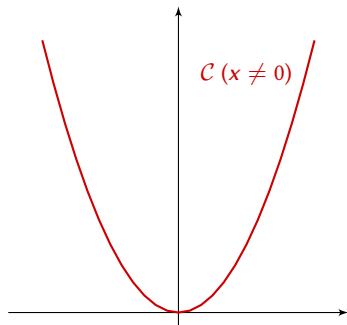
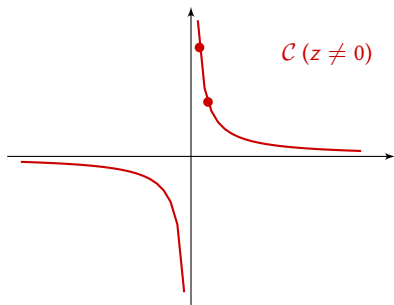


—  — $t \in k$

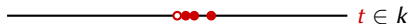
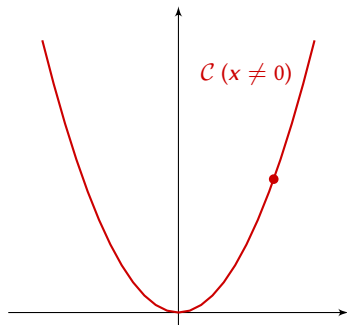
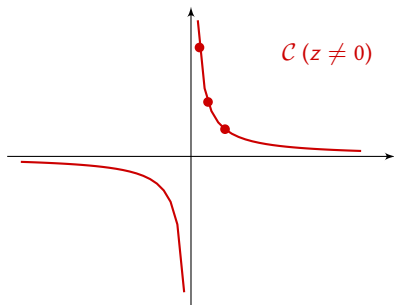
Back to example 2: pole at infinity



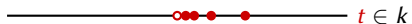
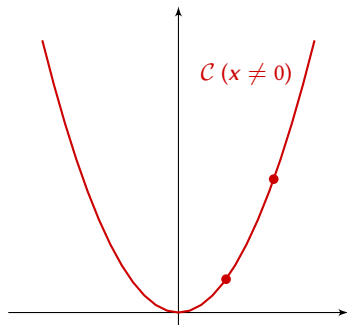
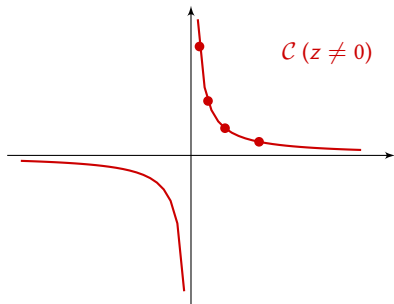
Back to example 2: pole at infinity



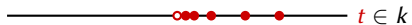
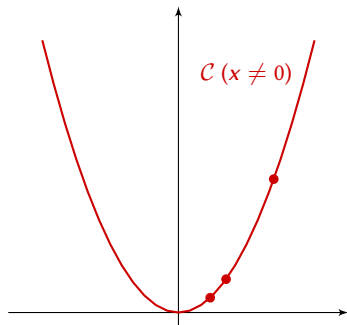
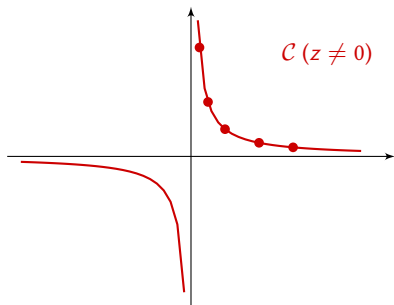
Back to example 2: pole at infinity



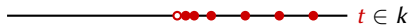
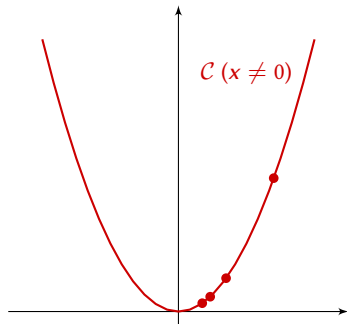
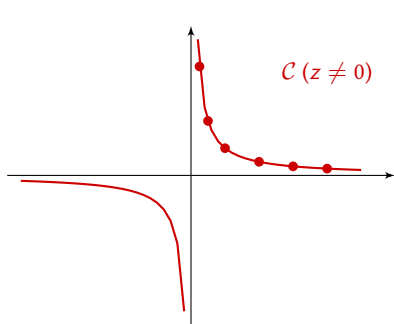
Back to example 2: pole at infinity



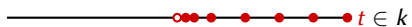
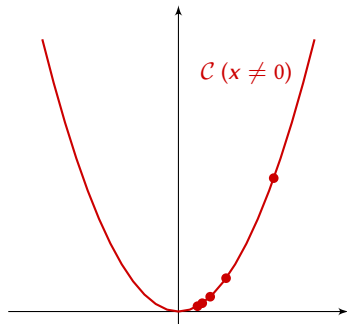
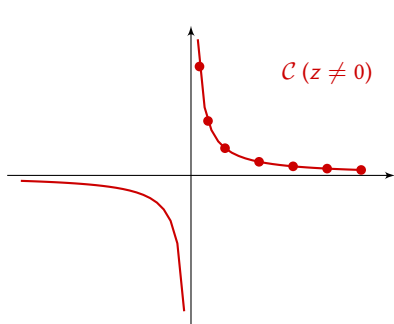
Back to example 2: pole at infinity



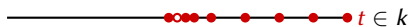
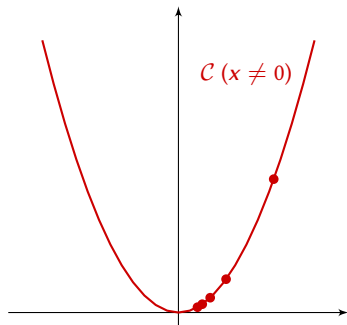
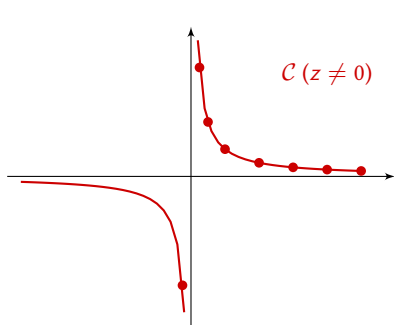
Back to example 2: pole at infinity



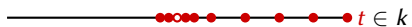
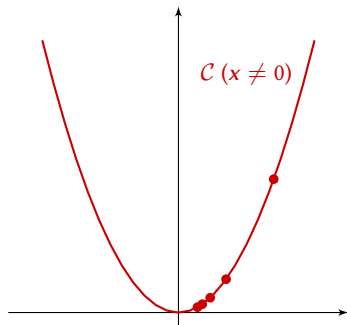
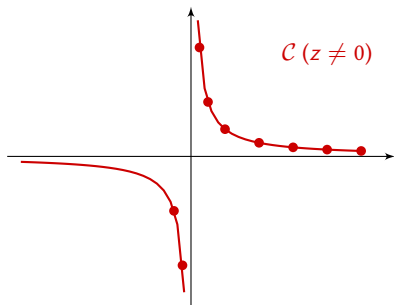
Back to example 2: pole at infinity



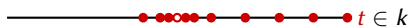
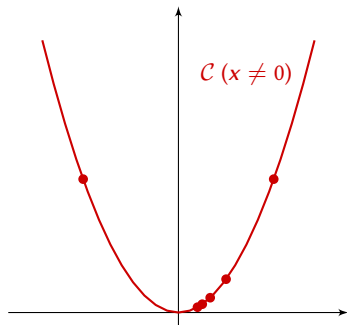
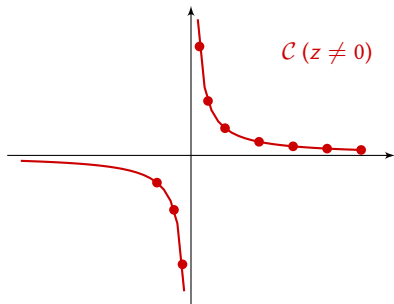
Back to example 2: pole at infinity



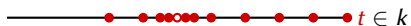
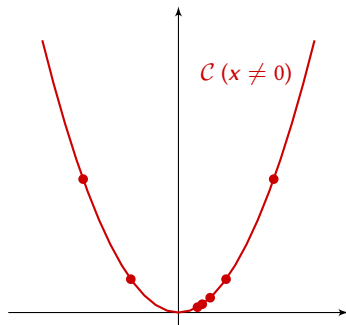
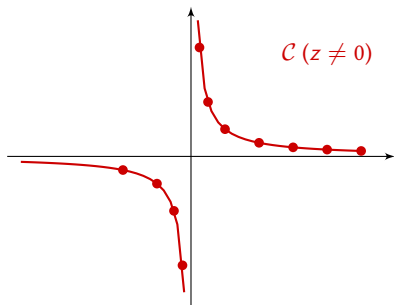
Back to example 2: pole at infinity



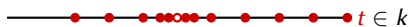
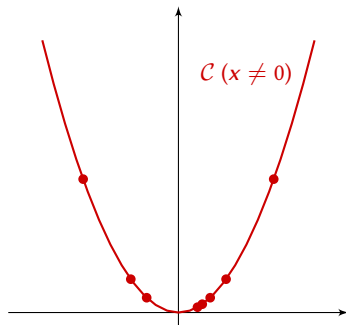
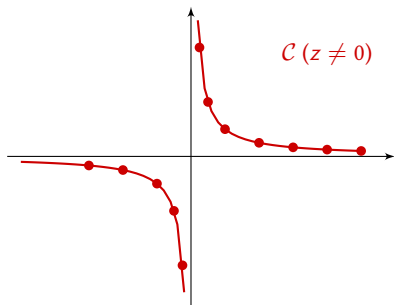
Back to example 2: pole at infinity



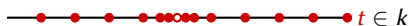
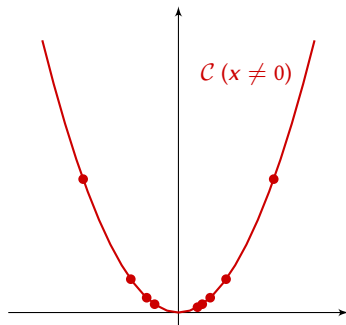
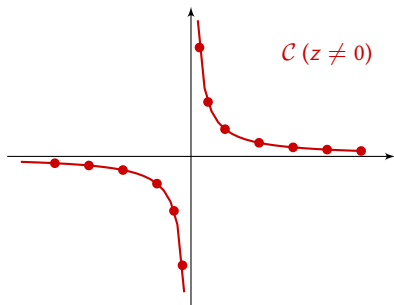
Back to example 2: pole at infinity



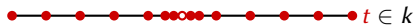
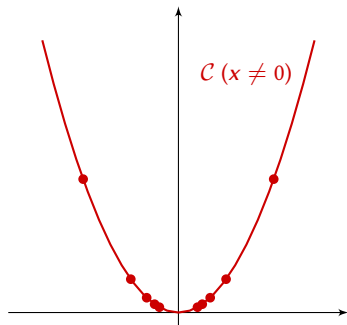
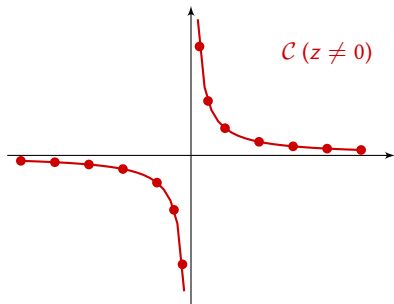
Back to example 2: pole at infinity



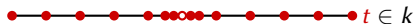
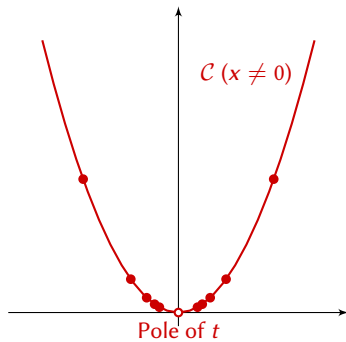
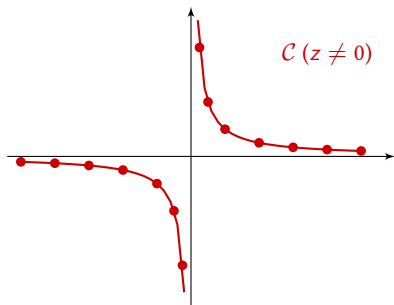
Back to example 2: pole at infinity



Back to example 2: pole at infinity



Back to example 2: pole at infinity



Full problem

Input: a polynomial $f \in k[X, Y]$ defining a curve \mathcal{C}

Output: $t(X, Y) \in k(X)[Y]/\langle f \rangle$ parameter for \mathcal{C}

Full problem

Input: a polynomial $f \in k[X, Y]$ defining a curve \mathcal{C}

Output: $t(X, Y) \in k(X)[Y]/\langle f \rangle$ parameter for \mathcal{C}

Hypotheses:

1. f is irreducible

Full problem

Input: a polynomial $f \in k[X, Y]$ defining a curve \mathcal{C} , a point $(x, y) \in \mathcal{C}$

Output: $t(X, Y) \in k(X)[Y]/\langle f \rangle$ parameter for \mathcal{C}

Hypotheses:

1. f is irreducible
2. (x, y) is a point of \mathcal{C} such that y is a single root of $f(x, Y)$

Full problem

Input: a polynomial $f \in k[X, Y]$ defining a curve \mathcal{C} , a point $(x, y) \in \mathcal{C}$

Output: $t(X, Y) \in k(X)[Y]/\langle f \rangle$ parameter for \mathcal{C}

Hypotheses:

1. f is irreducible
2. (x, y) is a point of \mathcal{C} such that y is a single root of $f(x, Y)$
3. $f_h(0 : 1 : 0) \neq 0$

Full problem

Input: a polynomial $f \in k[X, Y]$ defining a curve \mathcal{C} , a point $(x, y) \in \mathcal{C}$

Output: $t(X, Y) \in k(X)[Y]/\langle f \rangle$ parameter for \mathcal{C}

Hypotheses:

1. f is irreducible
2. (x, y) is a point of \mathcal{C} such that y is a single root of $f(x, Y)$
3. $f_h(0 : 1 : 0) \neq 0$

Key idea: t is a parameter iff it has exactly one pole on \mathcal{C} (including at infinity)

Full problem

Input: a polynomial $f \in k[X, Y]$ defining a curve \mathcal{C} , a point $(x, y) \in \mathcal{C}$

Output: $t(X, Y) \in k(X)[Y]/\langle f \rangle$ parameter for \mathcal{C}

Hypotheses:

1. f is irreducible
2. (x, y) is a point of \mathcal{C} such that y is a single root of $f(x, Y)$
3. $f_h(0 : 1 : 0) \neq 0$

Key idea: t is a parameter iff it has exactly one pole on \mathcal{C} (including at infinity)

- ▶ Integral bases tell us which functions do not have poles

Full problem

Input: a polynomial $f \in k[X, Y]$ defining a curve \mathcal{C} , a point $(x, y) \in \mathcal{C}$

Output: $t(X, Y) \in k(X)[Y]/\langle f \rangle$ parameter for \mathcal{C}

Hypotheses:

1. f is irreducible
2. (x, y) is a point of \mathcal{C} such that y is a single root of $f(x, Y)$
3. $f_h(0 : 1 : 0) \neq 0$

Key idea: t is a parameter iff it has exactly one pole on \mathcal{C} (including at infinity)

- ▶ Integral bases tell us which functions do not have poles
- ▶ ... but only on finite parts

Full problem

Input: a polynomial $f \in k[X, Y]$ defining a curve \mathcal{C} , a point $(x, y) \in \mathcal{C}$

Output: $t(X, Y) \in k(X)[Y]/\langle f \rangle$ parameter for \mathcal{C}

Hypotheses:

1. f is irreducible
2. (x, y) is a point of \mathcal{C} such that y is a single root of $f(x, Y)$
3. $f_h(0 : 1 : 0) \neq 0$

Key idea: t is a parameter iff it has exactly one pole on \mathcal{C} (including at infinity)

- ▶ Integral bases tell us which functions do not have poles
- ▶ ... but only on finite parts
- ▶ ... and we need a function with 1 pole

Overview of the algorithm

Split the projective plane into:

- ▶ The finite plane $A := \{z \neq 0\}$
- ▶ Part of the line at infinity $B := \{x \neq 0, z = 0\}$
- ▶ The last point at infinity $C := \{(0 : 1 : 0)\}$

Overview of the algorithm

Split the projective plane into:

- ▶ The finite plane $A := \{z \neq 0\}$
- ▶ Part of the line at infinity $B := \{x \neq 0, z = 0\}$
- ▶ The last point at infinity $C := \{(0 : 1 : 0)\}$

Algorithm:

1. Find a function P with 1 pole on the finite plane A

Overview of the algorithm

Split the projective plane into:

- ▶ The finite plane $A := \{z \neq 0\}$
- ▶ Part of the line at infinity $B := \{x \neq 0, z = 0\}$
- ▶ The last point at infinity $C := \{(0 : 1 : 0)\}$

Algorithm:

1. Find a function P with 1 pole on the finite plane A
2. Write equations characterizing functions with no pole on A

Overview of the algorithm

Split the projective plane into:

- ▶ The finite plane $A := \{z \neq 0\}$
- ▶ Part of the line at infinity $B := \{x \neq 0, z = 0\}$
- ▶ The last point at infinity $C := \{(0 : 1 : 0)\}$

Algorithm:

1. Find a function P with 1 pole on the finite plane A
2. Write equations characterizing functions with no pole on A
3. Write equations characterizing functions with no pole on the line at infinity B

Overview of the algorithm

Split the projective plane into:

- ▶ The finite plane $A := \{z \neq 0\}$
- ▶ Part of the line at infinity $B := \{x \neq 0, z = 0\}$
- ▶ The last point at infinity $C := \{(0 : 1 : 0)\}$

Algorithm:

1. Find a function P with 1 pole on the finite plane A
2. Write equations characterizing functions with no pole on A
3. Write equations characterizing functions with no pole on the line at infinity B
4. Solve them to find Q such that Q has no pole on A and $P + Q$ has no pole on B

Overview of the algorithm

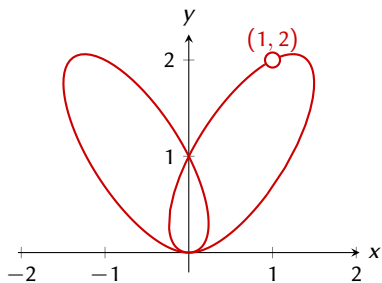
Split the projective plane into:

- ▶ The finite plane $A := \{z \neq 0\}$
- ▶ Part of the line at infinity $B := \{x \neq 0, z = 0\}$
- ▶ The last point at infinity $C := \{(0 : 1 : 0)\}$

Algorithm:

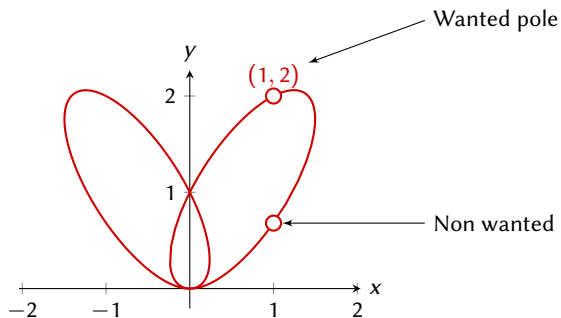
1. Find a function P with 1 pole on the finite plane A
2. Write equations characterizing functions with no pole on A
3. Write equations characterizing functions with no pole on the line at infinity B
4. Solve them to find Q such that Q has no pole on A and $P + Q$ has no pole on B
5. $P + Q$ is our parameter t

1. Finding a function with one pole



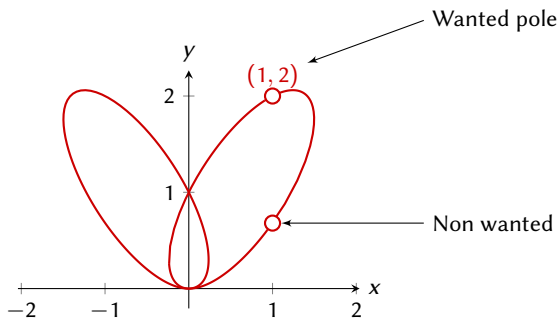
1. Finding a function with one pole

- ▶ $\frac{1}{X-x}$ would be nice if it didn't have more poles



1. Finding a function with one pole

- ▶ $\frac{1}{X-x}$ would be nice if it didn't have more poles
- ▶ We want a numerator which is 0 everywhere $f(x, Y)$ is 0, except at $Y = y$

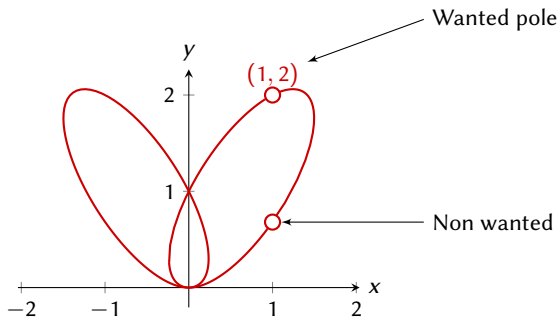


1. Finding a function with one pole

- ▶ $\frac{1}{X-x}$ would be nice if it didn't have more poles
- ▶ We want a numerator which is 0 everywhere $f(x, Y)$ is 0, except at $Y = y$

Construction

1. Write $f(x, Y) = (Y - y)g(Y)$ with $g(y) \neq 0$

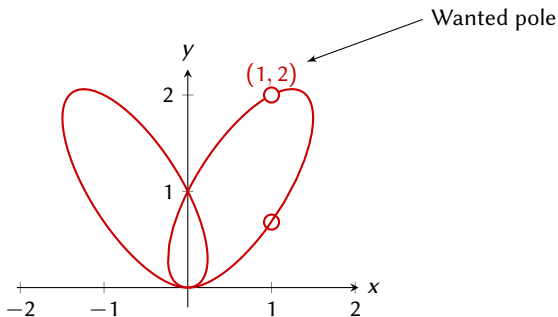


1. Finding a function with one pole

- ▶ $\frac{1}{X-x}$ would be nice if it didn't have more poles
- ▶ We want a numerator which is 0 everywhere $f(x, Y)$ is 0, except at $Y = y$

Construction

1. Write $f(x, Y) = (Y - y)g(Y)$ with $g(y) \neq 0$
2. P is $\frac{g(Y)}{X-x}$



2. Equations characterizing functions with no pole in A

1. Compute an integral basis b_0, \dots, b_{n-1} of $k(x)[y]/\langle f \rangle$
2. Q does not have a pole in A iff $Q \in k[x]b_0 + \dots + k[x]b_{n-1}$
3. Write an Ansatz $Q = \frac{\sum_{i+j \leq N} a_{ij}x^i y^j}{D(x)}$ where $N \in \mathbb{N}$ and $D \in k[x]$ are “sufficiently big”
4. Multiply out the denominators
5. Use reductions (e.g. ala Gröbner) to write $DQ = \bullet(x)Db_0 + \bullet(x)Db_{n-1} + r(x, y)$
6. The coefficients of r are linear in the a_{ij} , set them to 0 and obtain a system of equations

3. Equations characterizing functions with no poles in B

1. Compute an local integral basis c_0, \dots, c_{n-1} of $k(z)[y]/\langle f_z \rangle$
2. $P + Q$ does not have a pole in $B \setminus A$ iff $P + Q \in k[x]_{(z)}b_0 + \dots + k[x]_{(z)}b_{n-1}$
3. Forget the denominators not divisible by z
4. Multiply out the rest of the denominators z^d
5. Use reductions (e.g. ala Gröbner) to write $z^d(P + Q) = \bullet(x) z^d c_0 + \bullet(x) z^d c_{n-1} + s(x, y)$
6. The coefficients of s are linear in the a_{ij} , set them to 0 and obtain a system of equations

1. Split \mathcal{C} into $(\mathcal{C} \cap \{z = 1\}) \cup (\mathcal{C} \cap \{z = 0\})$
2. Compute P with exactly one pole at finite distance
3. Write an Ansatz for $Q = \frac{\sum_{i+j \leq N} a_{ij} x^i y^j}{D(x)}$
4. Compute an integral basis of $k(x)[y]/\langle f \rangle$
5. Find a linear system in the a_{ij} ensuring that Q does not have a pole at finite distance
6. Compute an integral basis of $k(z)[y]/\langle f_z \rangle$
7. Find a linear system in the a_{ij} ensuring that $P + Q$ does not have a pole at infinity
8. Solve the equations and find $t = P + Q$

Full process

1. Split \mathcal{C} into $(\mathcal{C} \cap \{z = 1\}) \cup (\mathcal{C} \cap \{z = 0\})$
2. Compute P with exactly one pole at finite distance
3. Write an Ansatz for $Q = \frac{\sum_{i+j \leq N} a_{ij} x^i y^j}{D(x)}$
4. Compute an integral basis of $k(x)[y]/\langle f \rangle$
5. Find a linear system in the a_{ij} ensuring that Q does not have a pole at finite distance
6. Compute an integral basis of $k(z)[y]/\langle f_z \rangle$
7. Find a linear system in the a_{ij} ensuring that $P + Q$ does not have a pole at infinity
8. Solve the equations and find $t = P + Q$
9. Eliminate Y from the system $(T - t, f)$ and solve in X to find $x(T)$
10. Eliminate X from the system $(T - t, f)$ and solve in Y to find $y(T)$